•	2 6
3/A.	The apparatus of claim 1/2 wherein the controller further comprises:
	a loop filter for providing control to the sensor apparatus, to the loop filter including:
	one or more integrators for providing a signal for controlling the sensor system;
	one or more derivative controllers for providing a signal for controlling the sensor
system	n;
	one or more proportional controllers for providing a signal for controlling the sensor
system	n; and
	a summer for combining the signals from the integrators, the derivative controllers, and
the pro	portional controllers.
	96
30,5	The apparatus of claim further comprising:
	a multiphase clock generator for providing clock signals for controlling the operation of
the ap	paratus, the clock generator including:
	a digital signal generator; and
	a data-independent clock resynchronization circuit coupled to the digital signal generator
	ampling clock signals.
	The apparatus of claim, further comprising: a sensor simulator for simulating the operation of a sensor, the simulator including:
35,6.	The apparatus of claim it further comprising:
	a sensor simulator for simulating the operation of a sensor, the simulator including;
	a filter adapted to receive one or more input signals and generate an output signal
represe	entative of the operating state of the sensor; and
	an input signal selector operably coupled to the filter adapted to controllably select the
input s	ignals as a function of the simulated operating state of the sensor.
71.	∂ 8
51,7%	The apparatus of claim further comprising:
	a device for testing the operation of the controller, the device comprising;
÷	a sensor simulator for simulating the operation of a sensor; and
J	a second controller coupled to the simulator.
2) 2/	The apparatus of claim, wherein the controller further comprises:
J. J.	a feedback control system for providing control to the apparatus, the feedback control
system	comprising:
0,010	a startup sequencer for selecting the mode of operation of the feedback control system;
and	a can application of the control of
	a loop filter coupled to the startup sequencer.
	system system the pro

a sense amplifier for sensing the position of the measurement mass within the sensor.

1	6 .	The apparatus of claim b, wherein the clock resynchronization circuit comprises:
2	•	a plurality of inverters;
3		a plurality of NOR gates coupled to the inverters;
4		a plurality of NAND gates coupled to the inverters;
5		a plurality of XNOR gates coupled to the NAND gates and the inverters;
6		a plurality of asynchronous set double-edge flip-flops coupled to the NOR gates; and
7		a plurality of asynchronous reset double-edge flip-flops coupled to the NOR gates.
	27	
1	3/16.	A method of controlling the operation of a sensor assembly, comprising:
2	•	using a controller to apply electrostatic forces to a sensor to create one or more sensor
3	operat	ing states; and
4		sequentially arranging the operating states into which the sensor is placed to create a
5	pluralit	y of operating modes for the sensor assembly.
	-6-	The method of claim 10 further comprising:
1	3611.	The method of claim 10 further comprising:
2		determining an operating mode of the sensor assembly;
3		adjusting a mode of operation of a loop filter in the sensor assembly;
4		providing feedback loop compensation to the sensor assembly during a start-up mode
5	of oper	ration for the sensor assembly; and
6		providing noise shaping to the sensor assembly during a sigma-delta mode of operation
7	for the	sensor assembly.
	391	The method of claim 70, wherein the sensor assembly includes a loop filter, one or more
1	1/2.	•
2		integrators, a proportional controller, the method further comprising:
3		placing a loop filter including one or more integrators, a proportional controller, and a
4	derivat	ive controller in a reduced-order operating mode;
5		sending a signal to the loop filter to control the operating mode of the loop filter; and
6		holding the integrators within the loop filter in a reset mode to place the loop filter in the
7	reduce	ed-order operating mode.
	40 6	The method of claim 1/2 further comprising:
1	/ ⁵ //3.	The method of claim 12 further comprising:
2		taking the integrators out of the reset mode to place the loop filter in a normal operating
3		when the sensor system is operating in a sigma-delta operating mode.
4	4/14.	The method of claim 12, wherein the operating mode of the loop filter further comprises:
1	. 74.	·
2		sending a signal to the loop filter indicating an operating mode of the sensor assembly; operating the loop filter in a reduced-order mode while the sensor assembly is operating

in a start-up mode;

operating the loop filter in the reduced-order mode for a predetermined period of time after the sensor assembly transitions from the start-up operating mode to a sigma-delta operating mode; and

operating the loop filter in a normal mode during the sigma-delta operating mode after the predetermined period of time during which the loop filter operates in reduced-order mode.

The method of claim 14, wherein the operating mode of the loop filter further comprises: operating the loop filter in a reduced-order mode while the sensor assembly is operating in the sigma-delta operating mode.

The method of claim further comprising: generating a clock signal for the sensor assembly, the generating including:

generating a first clock signal; and

resampling the first clock signal to generate a second clock signal to restore signal integrity and providing a timing relationship.

The method of claim of further comprising:

resampling an input signal to the sensor assembly, the resampling including:

resampling the input signal in a first level-sensitive latch, including one or more transmission gates, one or more NOR gates, and one or more inverters, on one edge of a clock input signal; and

resampling the input signal in a second level-sensitive latch, including one or more transmission gates, one or more NOR gates, and one or more inverters, acting in parallel with the first level-sensitive latch, on another edge of the clock input signal.

The method of claim 10 further comprising:

resampling an input signal to the sensor assembly, the resampling including:

resampling the input signal in a first level-sensitive latch, including one or more transmission gates, one or more NAND gates, and one or more inverters, on one edge of a clock input signal; and

resampling the input signal in a second level-sensitive latch, including one or more transmission gates, one or more NAND gates, and one or more inverters, acting in parallel with the first level-sensitive latch, on another edge of the clock input signal.

The method of claim 10, wherein the controller includes an analog control circuit, the method further comprising:

operating the analog control circuit by generating a first clock signal;

resampling the first clock signal to generate a second clock signal to restore signal

5	integrity and provide a proper timing relationship; and		
6	•	driving the analog control circuit using the second clock signal.	
	47	27	
1	<i>3</i> 6.	The method of claim 17 further comprising testing the controller, wherein the test	
2		comprises:	
3		connecting a sensor simulator to the controller;	
4		supplying an input signal of a known value to the sensor simulator;	
5		converting the input data to the sensor simulator into an output stream from the sensor	
6	simulator;		
7		sending the output stream from the sensor simulator to the controller;	
8		processing the output stream from the sensor simulator within the controller to create	
9	an output stream from the controller; and		
10		analyzing the output from the controller to determine the accuracy of the controller.	
	118	37	
1	21.	The method of claim 10 further comprising:	
2	•	offsetting the effects of external acceleration forces on the sensor assembly	
3	independent of sensor assembly orientation by applying electrostatic forces to a sensor element		
4	to off:	set the effects of the acceleration force.	
		Respectfully submitted,	

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